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# 256. ON SOME SYSTEMS OF PARTIAL DIFFERENTIAL EQUATION AND ON SOME CLASSES OF NON-ANALYTIC FUNCTIONS\*

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In the first part regular solutions [1] of the system

$$\frac{\partial u}{\partial x} - \frac{\partial v}{\partial y} = f(x, y, u, v); \qquad \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} = g(x, y, u, v),$$

for some special cases, are obtained. In the second part a system of partial equations of second order is solved. In the third part two classes of non-analytic functions are given in a closed form.

1.1. In this part we shall solve the following system of partial differential equations

$$\frac{\partial u}{\partial x} - \frac{\partial v}{\partial y} = f(x, y, u, v); \quad \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} = g(x, y, u, v)$$

(u=u(x, y), v=v(x, y)) for some special cases.

Multiplying the second equation of the system by i and adding it to the first, the left hand side becomes

$$\frac{\partial u}{\partial x} - \frac{\partial v}{\partial y} + i \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right).$$

This expression represents the areolare derivative of POMPEIU [2] multiplied by 2, or the operator B,

$$B = \frac{\partial}{\partial x} + i \frac{\partial}{\partial y}$$

which was introduced by BILIMOVIĆ, who called it deviation from being analytic [3].

Besides the operator B, in this paper we shall use its inverse operator S, introduced by FEMPL. In that case  $S \Phi(z, \overline{z}) = w$  denotes that  $Bw = \Phi(z, \overline{z})$ .

The following propreties of the operators B and S can be easily checked:

$$B(w_1 + w_2) = Bw_1 + Bw_2$$
,  $Bw_1w_2 = w_1Bw_2 + w_2Bw_1$ ,

<sup>\*</sup> Presented January 25, 1969 by D. S. Mitrinović and S. Fempl.

Bw = 0 if and only if w is an analytic function,

$$Bf(w) = f'(w) Bw, B\overline{z} = 2,$$

$$\Im f(z, w) Bw = \int f(z, w) dw + \alpha(z), \ \Im f(z, \overline{z}) = \frac{1}{2} \int f(z, \overline{z}) d\overline{z} + \alpha(z),$$

where in the last two relations a(z) represents an arbitrary analytic function.

### 1.2. Consider the following system

(1) 
$$\frac{\partial u}{\partial x} - \frac{\partial v}{\partial y} = \operatorname{Re} f\left(z, \frac{w}{z}\right), \quad \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} = \operatorname{Im} f\left(z, \frac{w}{z}\right),$$

where w = u + iv, z = x + iy,  $\overline{z} = x - iy$ .

Multiplying the second equation by i and adding it to the first, we get

$$Bw = f\left(z, \frac{w}{z}\right)$$

(The equation  $Bw = f\left(\frac{w}{z}\right)$  has been solved by S. FEMPL [4]).

Introduce the following substitution: w = tz. Then Bw = 2t + zBt and equation (2) becomes

i.e., 
$$\frac{Bt}{f(z, t) - 2t} = \frac{1}{z}, \text{ i.e., } \Im \frac{Bt}{f(z, t) - 2t} = \Im \frac{1}{z}.$$

Using the properties of the operator S, we get

$$\int \frac{1}{f(z, t) - 2t} dt = \frac{1}{2} \int \frac{1}{z} dz + P(z),$$

where P(z) is an arbitrary analytic function.

Let 
$$\Phi(z, t) = \int \frac{1}{f(z, t) - 2t} dt$$
. Then  $z = a(z) e^{2\Phi(z, t)}$ , where  $a(z) = e^{-2P(z)}$ 

is also an analytic function, is the solution of (2).

Therefore

$$x = \text{Re} [\alpha(z) e^{2\Phi(z, t)}], \quad y = -\text{Im} [\alpha(z) e^{2\Phi(z, t)}]$$

is the regular solution [1] of the system (1).

#### 1.3. Let

(3) 
$$\frac{\partial u}{\partial x} - \frac{\partial v}{\partial y} = \operatorname{Re} f\left(\frac{a(z)z + b(z)w + c(z)}{A(z)\overline{z} + B(z)w + C(z)}\right),$$

$$\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} = \operatorname{Im} f\left(\frac{a(z)\overline{z} + b(z)w + c(z)}{A(z)\overline{z} + B(z)w + C(z)}\right),$$

where a, b, c, A, B, C are analytic functions, and let  $\begin{vmatrix} a(z) & b(z) \\ A(z) & B(z) \end{vmatrix} \neq 0$ .

System (3) is equivalent to

(4) 
$$Bw = f\left(\frac{a(z)\overline{z} + b(z)w + c(z)}{A(z)\overline{z} + B(z)w + C(z)}\right).$$

The solution of (4) is

(5) 
$$w = \beta(z) + \Phi(\overline{z} - \alpha(z), z),$$

where  $t = \Phi(\zeta, z)$  is the solution of

(6) 
$$Bt = f\left(\frac{a(z)\zeta + b(z)t}{A(z)\zeta + B(z)t}\right) = F\left(z, \frac{t}{\zeta}\right),$$

(7) 
$$\zeta = \overline{z} - \alpha(z), \quad t = w - \beta(z),$$

and  $\alpha$ ,  $\beta$  are solutions of the system

(8) 
$$a(z) \alpha + b(z) \beta + c(z) = 0, \quad A(z) \alpha + B(z) \beta + C(z) = 0.$$

**Proof.** Let us show first that  $\alpha$ ,  $\beta$  are analytic functions. Apply the operator B on the system (8), and we get

$$a(z) B\alpha + b(z) B\beta = 0$$
,  $A(z) B\alpha + B(z) B\beta = 0$ .

Since the determinant of the above system is not zero, its only solutions are trivial  $B\alpha = B\beta = 0$ , i.e.,  $\alpha$  and  $\beta$  are analytic functions.

Let  $t = \Phi(\zeta, z)$  be the solution of the equation (6). Then

$$Bt = 2\Phi_1'(\zeta, z) = f\left(\frac{a(z)\zeta + b(z)t}{A(z)\zeta + B(z)t}\right)$$

where  $\Phi_1$  denotes the partial derivative with respect to the first argument However, starting from (5) we get  $Bw = 2\Phi_1'(\bar{z} - \alpha(z), z)$ , and according to (7): Bt = Bw.

Using (7), (8), we conclude that

$$\frac{a(z)\zeta + b(z)t}{A(z)\zeta + B(z)t} = \frac{a(z)\overline{z} + b(z)w + c(z)}{A(z)\overline{z} + B(z)w + C(z)}$$

and (5) is, therefore the solution of the equation (4).

In other words,

$$u = \operatorname{Re}\left[\beta\left(z\right) + \Phi\left(\overline{z} - \alpha\left(z\right), z\right)\right], \quad v = \operatorname{Im}\left[\beta\left(z\right) + \Phi\left(\overline{z} - \alpha\left(z\right), z\right)\right]$$

is the regular solution of the system (3).

**1.4.** The system

$$\frac{\partial u}{\partial x} - \frac{\partial v}{\partial y} = \operatorname{Re}\left[f(z, w) g(z, \overline{z})\right], \quad \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} = \operatorname{Im}\left[f(z, w) g(z, \overline{z})\right]$$

has the following complex form

(9) 
$$Bw = f(z, w) g(z, \overline{z}), \quad \text{i.e.,} \quad \frac{Bw}{f(z, w)} = g(z, \overline{z}).$$

(A special case of this equation,  $Bw = f(w) g(\overline{z})$ , has been solved in [3])

Considering the properties of the operator B, we have

$$\int \frac{1}{f(z, w)} dw = \frac{1}{2} \int g(z, \overline{z}) d\overline{z} + P(z),$$

where P(z) is an analytic function.

The above expression represents the solution of the equation (9).

Example. The system

(10) 
$$\frac{\partial u}{\partial x} \frac{\partial v}{\partial y} = \frac{(x^2 - y^2)u + 2xyv}{x^2 + y^2}, \quad \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} = \frac{(x^2 - y^2)v - 2xyu}{x^2 + y^2}$$

becomes

$$Bw = \frac{w\overline{z}}{z}$$

and the solution is, therefore,

$$\int \frac{dw}{w} = \frac{1}{2} \int \frac{\overline{z}}{z} d\overline{z} + P(z).$$

After some rearranging, and putting  $P_1(z) = \log P(z)$ , we get

$$w = P_1(z) \exp\left(\frac{1}{4} \frac{\overline{z^2}}{z}\right).$$

If  $P_1(z) = a(x, y) + i \beta(x, y)$ , we have

$$u(x, y) = \exp\left(\frac{x^3 - 3xy^2}{4(x^2 + y^2)}\right) \left[\alpha(x, y)\cos\frac{3x^2y - y^3}{4(x^2 + y^2)} + \beta(x, y)\sin\frac{3x^2y - y^3}{4(x^2 + y^2)}\right];$$

$$v(x, y) = \exp\left(\frac{x^3 - 3xy^2}{4(x^2 + y^2)}\right) \left[\beta(x, y)\cos\frac{3x^2y - y^3}{4(x^2 + y^2)} - \alpha(x, y)\sin\frac{3x^2y - y^3}{4(x^2 + y^2)}\right],$$

and this is the regular solution of the system (10).

2. Starting from the operator B, operators of higher order can be defined:

$$B_1 = B$$
,  $B_{n+1} = B(B_n)$ ,  $n > 1$ 

For the complex function w, the expression  $B_n w$  is called *n-th deviation* from being analytic (n-th deviation).

In this part we shall solve an equation which involves the operator  $B_2$ . Let

$$(11) B_2 w = f(z, w).$$

Then

(12) 
$$\int \frac{dw}{\sqrt{2\int f(z,w)\,dw + \alpha(z)}} = \frac{\overline{z}}{2} + \beta(z)$$

is the solution of the equation (11), where  $\alpha$ ,  $\beta$  are arbitrary analytic functions.

**Proof.** Using the properties of the operator  $\mathcal{S}$ , we see that (12) can be written in the form

Applying the operator B on the equation (13), we get

(14) 
$$\frac{Bw}{\sqrt{2 \Im f(z, w) Bw + \alpha(z)}} = 1, \quad \text{i.e.,} \quad Bw = \sqrt{2 \Im f(z, w) Bw + \alpha(z)}.$$

It then follows that

$$B_2 w = \frac{2 f(z, w) Bw}{2 \sqrt{2 \Im f(z, w) Bw + \alpha(z)}}$$

or, using (14),

$$B_2w=f(z, w).$$

The given solution of the equation (11) facilitates the method of solving the system of second order partial differential equation of the form

$$\frac{\partial^2 u}{\partial x^2} - 2 \frac{\partial^2 v}{\partial x \partial y} - \frac{\partial^2 u}{\partial y^2} = \operatorname{Re} f(z, w), \qquad \frac{\partial^2 v}{\partial x^2} + 2 \frac{\partial^2 u}{\partial x \partial y} - \frac{\partial^2 v}{\partial y^2} = \operatorname{Im} f(z, w).$$

EXAMPLE. System

$$\frac{\partial^2 u}{\partial x^2} - 2 \frac{\partial^2 v}{\partial x \partial y} - \frac{\partial^2 u}{\partial y^2} = (x^2 - y^2) e^{-2u} \cos 2v + 2xye^{-2u} \sin 2v$$

$$\frac{\partial^2 v}{\partial x^2} + 2 \frac{\partial^2 u}{\partial x \partial y} - \frac{\partial^2 v}{\partial y^2} = 2xye^{-2u} \cos 2v - (x^2 - y^2) e^{-2u} \sin 2v$$

becomes

(15)

(16) 
$$e^{2w}B_2w = z^2$$
, where  $w = u + iv$ ,  $z = x + iy$ .

The solution of (16) is

$$\varphi_1(z) e^{w} = z \operatorname{ch} \left[ \varphi_1(z) \frac{\overline{z}}{2} + \varphi_2(z) \right], \qquad (\varphi_1, \varphi_2 \text{ arbitrary analytic functions})$$

and, therefore,

$$u = \operatorname{Re} \log \frac{z}{\varphi_{1}(z)} \operatorname{ch} \left[ \varphi_{1}(z) \frac{\overline{z}}{2} + \varphi_{2}(z) \right], \quad v = \operatorname{Im} \log \frac{z}{\varphi_{1}(z)} \operatorname{ch} \left[ \varphi_{1}(z) \frac{\overline{z}}{2} + \varphi_{2}(z) \right]$$

represents the solution of the system (15).

- 3. Finally, we give two classes of non-analytic functions in a closed form.
- 3.1. Any non-analytic function of the form

(17) 
$$w = \varphi(z) + \sum_{\nu=1}^{n} \varphi_{\nu}(z) e^{\frac{a_{\nu}}{2} z},$$

where  $\varphi_{\nu}(z)$  are arbitrary analytic functions, and  $\alpha_{\nu}$  ( $\nu = 1, \ldots, n$ ) are *n*-th roots of unity has the property that the difference between it and its *n*-th deviation is an analytic function  $\varphi(z)$ .

**Proof.** The following equation is to be solved:

$$(18) w - B_n w = \varphi(z)$$

Since the general solution of the equation  $w - B_n w = 0$  is [5]

$$w = \sum_{\nu=1}^{n} \varphi_{\nu}(z) e^{\frac{\alpha_{\nu}}{2}}$$

using the method given in [6] we see that the general solution of (18) is (17).

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3.2. Any non-analytic function of the form

(19) 
$$w = \sum_{\nu=1}^{n} P_{\nu}(z) \exp\left(\frac{\overline{z}}{2 \alpha_{\nu}(z)}\right)$$

where  $P_{\nu}(z)$  are arbitrary analytic functions, and  $\alpha_{\nu}(z)$  ( $\nu = 1, \ldots, n$ ) are n branches of the function  $\sqrt[n]{\varphi(z)}$ , has the property that the quotient between it and its *n*-th deviation is an analytic function  $\varphi(z)$ .

**Proof.** The following equation is to be solved

$$\frac{w}{B_n w} = \varphi(z),$$

i.e.,

$$B_n w - \frac{1}{\varphi(z)} w = 0.$$

This type of equation has been solved in [7], from where it can be seen that (19) is the general solution of the equation (20).

In the case when n=1, both given classes of non-analytic functions have been determined by S. FEMPL [8].

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